# DRAW WIRE SENSOR



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# Series SX80

#### **Key-Features:**

_	Measurement	ranges	from	1000	to	3000	mm
_	MEGSULEINERL	Iallues		1000	LU	3000	

- Analog Output: Potentiometer, 0...10 V, 4...20 mA
- Digital Output Incremental: RS422 (TTL), push-pull
- Digital Output Absolute: CANopen, SSI, Profibus, EtherCAT, Profinet
- Linearity up to ±0.02% of full scale
- Protection class up to IP67
- Temperature range -20...+85 °C (optional -40 °C or +120 °C)
- High dynamics
- High interference immunity factor
- Customised versions available

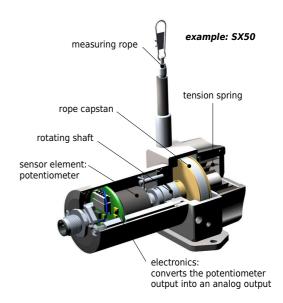


#### INTRODUCTION

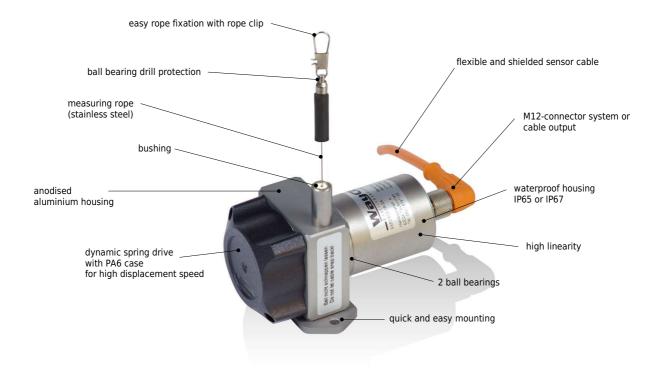
WayCon Positionsmesstechnik GmbH is a manufacturer of high quality draw wire position sensors for industrial use. Due to its small overall size, its short assembly time and its possible customisation, the SX sensor technology is a cost-effective and flexible solution for a wide range of industrial applications. The dynamics of the draw wire transducer allows a high motion speed and acceleration of the measuring target. Its rugged design and high quality makes applications in harsh industrial environments possible. Special instruments are available with mounting service of encoder on site, as well as customised versions of housing.

#### Sensor principle:

The key component of a draw wire sensor is a highly flexible steel wire rope, that is winded single-layered on an ultra light capstan. This capstan is connected to the sensor housing by a pre-stressed spring. The end of the steel wire rope, that is equipped with a rope clip gets connected to the target object. As soon as the distance between sensor and target object changes, the steel wire rope gets pulled out of the sensor and is rolled off the capstan (or vice versa). The shaft of the capstan is connected to a potentiometer (for analog output signals), or to an encoder (for digital output signals). If there is a rotation of the capstan due to a change in the distance to the target object, the sensor element will turn proportionally. This way the potentiometer, or the encoder converts a linear movement into a proportional electrical signal. If a standard analog output signal, like 0...10 V or 4...20 mA is needed, the sensor is equipped with an additional electronics.



# SPECIAL FEATURES



#### **WARNING NOTICES**

- Don't let the rope snap back. If the rope is retracted freely, this may lead to injuries (whiplash effect) and the device may be damaged. Caution when unhooking and retracting the rope into the sensor.
- Never exceed the specified measurement range when extracting the rope!
- Do not try to open the device. The stored energy of the spring drive may lead to injuries when being mishandled.
- Do not touch the rope when operating the sensor.
- Avoid guiding the rope over edges or corners. Use a deflection pulley instead.
- Do not operate the sensor if the rope is buckled or damaged. A ripping of the rope may lead to injuries or a damaging of the sensor.





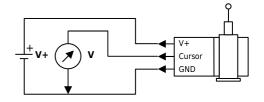
# TECHNICAL DATA ANALOG OUTPUT

Measurement range *	[mm]	1000	1500	2000	2500	3000		
Linearity	[%]	0.15	0.15	0.10	0.10	0.10		
Improved linearity (optional)	[%]	0.10	0.10	0.05	0.05	0.05		
Resolution				see types of output table	e below			
Sensor element				Hybrid Potentiome	ter			
Connection			connector output	M12 axial or cable outp	out axial 2 m (TPE cable)			
Protection class			IP65, optional IP67					
Humidity		maximum 90 % relative, no condensation						
Temperature	[°C]	standard: -20+85 / optional: -40+85 / optional: -20+120 °C (only with Potentiometer (1R) and cable output (KA))						
Mechanical data		extraction force, maximum velocity and maximum acceleration see table page 13						
Life expectancy		approx. 2 million full strokes						
Weight	[g]	300 to 500, depending on the measurement range						
Housing		aluminium, titanium-grey anodised, spring case PA6						
Accessories		cables, connectors, digital displays, deflection pulley, rope extensions, magnetic clamp (see pages 11 and 12)						

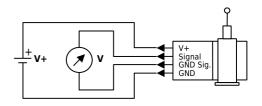
<sup>\*</sup> other ranges on request

# TYPES OF ANALOG OUTPUT

Output: Potentiometer (voltage divider)						
Output	1 kΩ					
Supply	max. 30 V					
Recommended cursor current	< 1 µA					
Resolution	theoretically unlimited, limited by the noise					
Noise	dependent on the quality ot the power supply					
Working temperature	-20+85 °C , optional: -40+85 °C / -20+120 °C					
Temperature coefficient	± 0.0025 %/K					

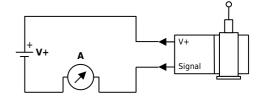


Output: Voltage 010 V	
Output	010 V, galvanically isolated, 4 conductors
Supply	1230 VDC
Current consumption	max. 22.5 mA (unloaded)
Output current	max. 10 mA, min. load 10 kOhm
Dynamics	< 3 ms from 0100 % and 1000 %
Resolution	limited by the noise
Noise	3 mV $_{\rm ss}$ typical, max. 37 mV $_{\rm ss}$
Inverse-polarity protection	yes, infinite
Short-circuit proof	yes, permanent
Working temperature	-20+85 °C , optional: -40+85 °C
Temperature coefficient	0.0037 %/K
Electromagnetic compatibility (EMC)	according to EN 61326-1:2006



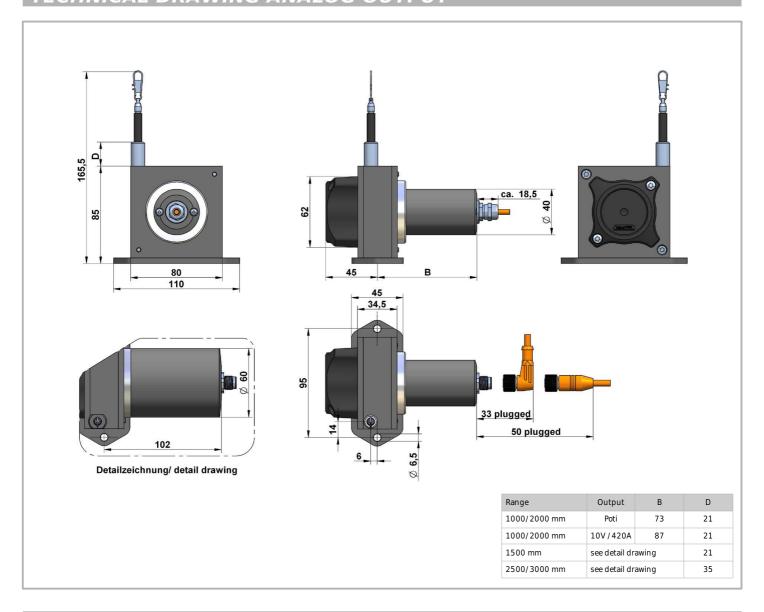
Note: GND Sig. and GND may be connected in a 3-wire system.

Output: Current 420 mA	
Output	420 mA, 2 conductors
Supply	1230 VDC
Output current	max. 50 mA in case of error
Dynamics	< 1 ms from 0100 % and 1000 %
Resolution	limited by the noise
Noise	$0.03 \text{ mA}_{ss} = 6 \text{ mV}_{ss}$ an 200 Ohm
Inverse-polarity protection	yes, infinite
Working temperature	-20+85 °C , optional: -40+85 °C
Temperature coefficient	0.0079 %/K
Electromagnetic compatibility (EMC)	according to EN 61326-1:2006



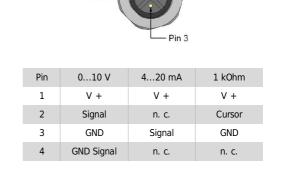


# TECHNICAL DRAWING ANALOG OUTPUT



# **ELECTRICAL CONNECTION ANALOG OUTPUT**

#### Cable output Cable type TPE, flexible Cable direction axial Length standard: 2 m, (others on request) Diameter 4.5 mm 0.25 mm<sup>2</sup> Wire fixed installation -30...+85 °C Temperature flexible installation -20...+85 °C Cable colour 0...10 V 4...20 mA 1 kOhm brown V + V + V + white Signal Cursor n. c. blue GND GND Signal black GND Signal n. c. n. c.



Pin 1

Connector output, M12, 4 poles



# TECHNICAL DATA DIGITAL OUTPUT INCREMENTAL

Measurement range *	[mm]	1000 / 1500 / 2000 / 2500 / 3000
Linearity	[%]	0.05, independent of the measurement range
Improved linearity (optional)	[%]	0.02, independent of the measurement range
Selectable resolution	[Pulses/mm]	0.5 / 1.25 / 2.5 / 5 / 10 / 25 (this resolution can be raised by the factor 4 using quadruple edge detection)
Z-Pulse distance	[mm]	200
Sensor element		Incremental-Encoder (with optical code disk)
Output signal		A/B-Pulses (90° phase-delayed), Z-Pulse (plus inverted pulses $A_{not}$ , $B_{not}$ , $Z_{not}$ )
Connection		M12 connector output or cable output with 2.0 m cable (PVC), open ends
Protection class		IP65, optional IP67
Humidity		maximum 90 % relative, no condensation
Temperature range	[°C]	-20+85
Mechanical data		extraction force, maximum velocity and maximum acceleration see table page 13
Life expectancy		approx. 2 million full strokes
Weight	[g]	approx. 750
Housing		aluminium, titanium-grey anodised, spring case PA6
Accessories		digital displays, deflection pulley, rope extensions, magnetic clamp (see pages 12 and 13)

\* other ranges on request

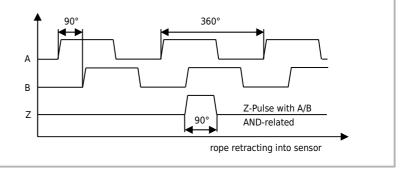
Electrical Data		Linedriver L	Push-Pull G		
		RS422 (TTL-compatible)			
Power supply +V	[VDC]	5, ±5 %	830		
Current consumption (no load)	[mA]	typical 40, max. 90	typical 40, max. 100		
Load/ Channel	[mA]	max. ±20	max. ±40		
Pulse frequency	[kHz]	max. 300	max. 200		
Signal level high	[V]	min. 2.5	min. +V - 3		
Signal level low	[V]	max. 0.5	max. 0.5		
Recommended circuit		Sensor Circuit $+5 \text{ V}$ $A$ $0 \text{ V}$ $Z = 120 \text{ Ohm}$	Sensor Circuit  A  A  A  A  A  A  A  A  A  A  A  A  A		

# OUTPUT SIGNAL DIGITAL OUTPUT INCREMENTAL

#### Output signal

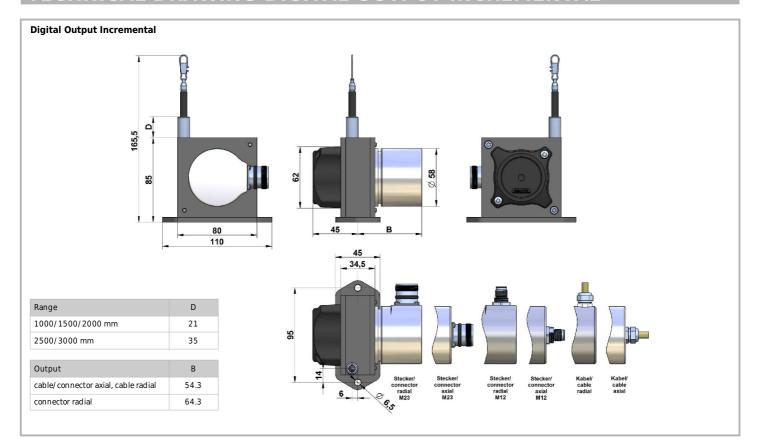
Pulses A and B are  $90^{\circ}$  phase-delayed (detection of direction). The Z-Pulse is emitted once per turn. The Z-Pulse distance is 125 mm (= circumference of the rope drum) and can be used as a reference mark.

Th diagram shows the signal without inverted signals; time line for return of rope.





# TECHNICAL DRAWING DIGITAL OUTPUT INCREMENTAL



#### CONNECTION DIGITAL OUTPUT INCREMENTAL

Signal	0 V	+V	0 V <sub>sens</sub> *	+V sens *	Α	A <sub>Not</sub>	В	B <sub>Not</sub>	Z	Z <sub>Not</sub>	screen
Connector M23, 12-pole	10	12	11	2	5	6	8	1	3	4	housing
Connector M12, 8-pole	1	2	-	-	3	4	5	6	7	8	housing
Cable output	white	brown	black	violet	green	yellow	grey	pink	blue	red	housing

\* For Linedriver L only. For long cable lengths it may occur that the operating voltage at the sensor does not suffice due to the output resistance. With the sensor lines 0 V 

+V: Encoder power supply +VDC

0 V:

Using the sensor outputs of the encoder, the voltage 0 V<sub>sens</sub> / +V<sub>sens</sub>:

present can be measured and if necessary increased accordingly

Encoder power supply ground GND (0 V) B, B<sub>Not</sub>: Incremental output channel B Z, Z<sub>Not</sub>: Reference signal

#### Connector output, M23, 12 poles



Connector output, M12, 8 poles



#### **Cable output**

A, A<sub>Not</sub>:

Cable type	PVC, flexible
Cable direction	radial or axial
Length	2.0 m
Diameter	ø 4.5 mm
Wires	8 (push-pull) and 10 (linedriver) x 0.14 $\mbox{mm}^{2}$
Temperature	fixed installation -30+85 °C
	flexible installation -20+85 °C
Assignment	see table above

Incremental output channel A



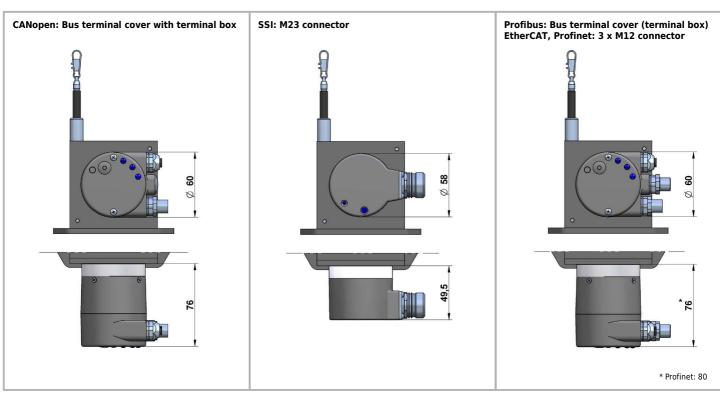
# TECHNICAL DATA DIGITAL OUTPUT ABSOLUTE

		CANopen	SSI	Profibus-DP	EtherCAT	Profinet		
Measurement range	[mm]	1000 / 1500 / 2000 / 2500 / 3000						
Linearity	[%]	0.05, independent of the measurement range						
Improved linearity (optional)	[%]		0.02, indep	pendent of the measurer	nent range			
Resolution scalable (with Software)		yes	no	yes	yes	yes		
Standard resolution	[Pulses/mm]	40.96	20.48	40.96	40.96	40.96		
	[Bit]	13	12	13	13	13		
Maximum resolution	[Pulses/mm]	327.68	-	327.68	327.68	327.68		
	[Bit]	16	-	16	16	16		
Sensor element			Multitum-Abs	colute-Encoder (with option	cal code disk)			
Connection		cable gland radial	1 x connector M23	cable gland radial	3 x connector M12	3 x connector M12		
		2 x	radial, 12 poles	3 x	4 pole, radial	4 pole, radial		
Power supply	[VDC]		1030 (reverse	polarity protection of th	e power supply)			
Current consumption (no load, 24 V)	[mA]	max. 100	max. 50	max. 120	max. 120	max. 200		
Protection class				IP65, optional IP67				
Humidity			max. 9	90 % relative, no conder	sation			
Temperature	[°C]			-20+80				
Mechanical data		extra	action force, maximum v	elocity and maximum a	cceleration see table pag	je 14		
Life expectancy		approx. 2 million full strokes						
Weight	[g]	approx. 1100						
Housing		aluminium, titanium-grey anodised, spring case PA6						
Special cables needed		yes	yes	yes	yes	yes		
Accessories		cable, connector, digital display, deflection pulley, rope extensions, magnetic clamp (see pages 12 and 13)						

Other encoder types are available on request

# TECHNICAL DRAWING DIGITAL OUTPUT ABSOLUTE

Note: for dimensions of the sensor housing please see page 4.





# **DESCRIPTION CANopen**

Parameters of the CANopen Interface					
Code	Binary				
Interface	CAN High-Speed acc. to ISO 11898, Basic- and Full-CAN, CAN Specification 2.0 B				
Protocol	CANopen profile DS406 V3.2 with manufacturer-specific add-ons				
Baud rate	10 1000 kbit/s (can be set via DIP switches/ Software configurable)				
Node address	1127 (can be set via rotary switches/ Software configurable)				
Termination switchable	can be set via DIP switches/ Software configurable				
SET Button (Option)	Zero or defined value option				
LED	LED is ON with the following fault conditions: Sensor error (internal code or LED error) too lowvoltage, over-temperature				

#### **Electrical connection CANopen**

	Bus out				Bus in					
Signal	CAN_GND	CAN_L	CAN_H	0 V	+V	0 V	+V	CAN_L	CAN_H	CAN_GND
Abbreviation	CG	CL	СН	0 V	+V	0 V	+V	CL	СН	CG

# DESCRIPTION SSI

Parameters of the SSI interface					
Output driver	RS485 Transceiver-type				
Permissible load/channel	max. ±20 mA				
Signal level	HIGH: typ 3.8 V				
	LOW: with $I_{Load} = 20$ mA typ 1.3 V				
Resolution	12 bit				
Code	Gray				
SSI clock rate	ST-resolution: 50 kHz2 MHz				
Monoflop time	≤ 15 µs				
Data refresh rate	≤ 1 µs				
Status and Parity bit	on request				

#### SET Input (optional)

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS-C. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the power supply must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

SET Input	
Input	active HIGH
Input type	comparator
Signal level	HIGH: min 60% of +V, max. +V
(+V = power supply)	LOW: max. 25% of +V
Input current	<0.5 mA
Min. pulse duration (SET)	10 ms
Input delay	1 ms
New position data readable after	1 ms
Internal processing time	200 ms

#### **Electrical connection SSI**

		Cable (Isolate unused wires individually before initial start-up)											
Signal	0V	+V	C+	C-	D+	D-	SET	DIR	Status	n.c.	n.c.	n.c.	Н
PIN	1	2	3	4	5	6	7	8	9	10	11	12	shield

+ V: Encoder power supply +VDC SET: SET Inpu

0 V: Encoder power supply GND (0 V) DIR: Direction input: If this input is active, output values are counted

C+, C-: Clock signal backwards (decrease) when the shaft is turning clockwise.

D+, D-: Data signal H: Plug connector housing (Shield)



# DESCRIPTION PROFIBUS DP

Parameters of the Profibus DP interface					
Code	Binary				
Interface	Profibus DP 2.0 Standard (DIN 19245 Part 3), RS485 Driver galvanically isolated				
Protocol	Profibus Encoder Profile V1.1 Class1 and Class2 with manufacturer-specific add-ons				
Baud rate	maximum 12 Mbit/s				
Device address	1127 (set by rotary switches)				
Termination switchable	set by DIP switches				
SET Button (Option)	Zero or defined value option				
LED	LED is ON with the following fault conditions: Sensor error, Profibus error				

#### **Electrical connection Profibus**

	Bus IN				Bus OUT			
Signal	В	Α	0 V	+V	0 V	+V	В	Α
Terminal	1	2	3	4	5	6	7	8

The shield of the connection cable must be connected over a large area via the cable gland.

# DESCRIPTION EtherCAT

Parameters of the I	Parameters of the Ether CAT Interface					
Code	Binary					
Protocol	EtherNet / EtherCAT					
Modes	Freerun, Distributed Clock					
Diagnostic LED red	LED is ON with the following fault conditions: Sensor error (internal code or LED error), low voltage, over-temperature					
Run LED green	LED is ON with the following conditions: Preop-, Safeop and Op-State (EtherCAT Status machine)					
2 x Link LEDs yellow	LED is ON with the following conditions (Port IN and Port OUT): Link detected					

#### **Electrical connection EtherCAT**

	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1_2
Bus Port in	Abbreviation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3
Power	Signal	Voltage +	-	Voltage -	-	4 3
aummlu.	Abbreviation	+V	-	0 V	-	
supply	PIN	1	2	3	4	1 2
	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1 2
Bus Port out	Abbreviation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3



# **DESCRIPTION PROFINET**

Parameters of the Profinet interface					
Code	Binary				
Protocol	PROFINET 10				
LED Link1/Link2	two coloured: green = active link				
	yellow = data transfer				

#### Ezturn Software for Profinet (supplied with the encoder)

- Monitoring of cyclic data (e.g. position, speed)
- Monitoring of acyclic data (e.g. IMO, electronic name plate, encoder parameters, warnings and error messages, preset)
- Setting of preset values
- Firmware updates via the bus

#### **Electrical connection Profinet**

	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1 2
Bus Port 1	Abbreviation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3
Power	Signal	Voltage +	-	Voltage -	-	4 3
cumply	Abbreviation	+V	-	0 V	-	
supply	PIN	1	2	3	4	1 2
	Signal	Transmit data +	Receive data +	Transmit data -	Receive data -	1 2
Bus Port 2	Abbreviation	TxD+	RxD+	TxD-	RxD-	D coded
	PIN	1	2	3	4	4 3



# OPTIONS

Option	Order code	Description
Protection class IP67 (instead of IP65)	IP67	Use option IP67, if sensor will operate in a humid environment.
		The regular ball bearings are replaced by stainless steel ball bearings.
		Note that with this option there may occur a light hysteresis in the output signal due to the special sealing
		The max. acceleration is reduced to 60 % of the specified value.
Corrosion protection by HARTCOAT®	СО	All components of the housing and the inner mechanics get HARTCOAT® coated.
		This coating is a hard-anodic oxidation that protects the sensor from corrosion by aggressive media
		(e. g. sea water) with a hard ceramics-like layer
		The regular ball bearings are replaced by stainless steel ball bearings.
Best corrosion protection	ICP	This option combines the options CO (HARTCOAT®-coating) and IP67 (protection class IP67).
		In addition, a increased corrosive protection is achieved by the use of special components.
Increased temperature range Low	TEMP-40-SX-ST	
only in combination with analog output		(up to +85°C) possible.
Increased temperature range High	TEMP120	Sensors with potentiometer output (1R) can be operated from -20 to +120 °C when this option is used.
only in combination with potentiometer 1R		(NOT in combination with analog or digital output signals)
Changed rope outlet	S1, S2, S3	S1: rope outlet sideways at the top
		S2*: rope outlet sideways at the bottom
		S3*: rope outlet on the bottom
		Seilaustritt Seilaustritt
		* with modified mounting plate
	1/1 1/2 1/2	see page 13  Standard sideways, apposite to the rape outlet
Changed cable or	K1, K2, K3	Startdard: Sideways, opposite to the rope oddet
connector orientation		K1: at the top
only for digital incremental output		K2: sideways, same side as the rope outlet
and digital incremental output		K3: at the bottom
		1
Ring eye	RI20	The end of the wire rope is equipped with a ring eye
ning eye	NIZO	instead of a rope clip.
		Inside diameter 20 mm
Rope fixation by M4 thread	M4	Optional, pivoted rope fixation with screw thread M4, length 22 mm.
		Ideal for attachment to through holes or thread holes M4.
		rope clip with drill protection \
		(standard)
		Optional M4-fixation
Inverted output signal	IN	The analog signal of the sensor is increasing by extracting the rope (standard).
only in combination with analog output		Option IN inverts the signal, i. e. the signal of the sensor declines by extracting the rope.
		<b>A</b>
		output signal
		10V/20mA ————————————————————————————————————
		Thereto I
		0V/4mA standard range
		vetract ← rs extract
		•



#### **ACCESSORIES**

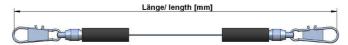
# Deflection pulley - UR2 The rope must be extracted from the sensor vertically. The maximum variation from the vertical is 3°. A deflection pulley allows a change in the direction of the wire rope. Several pulleys may be used. The rope clip must not be guided over the deflection pulley. material: anodised aluminium, POM mounting: by 2 hexagon socket or countersunk screws M6, vertical or horizontal mounting possible. Ball bearings: with special low temperature grease and RS-sealing. Temperature: -40...+80 °C.

#### Rope extension - SV

For bridging a greater distance between the measuring target and the sensor a rope extension can be applied. The rope clip must not be guided over the deflection pulley.

Please specify the length needed in your order (XXXX). The minimum length is 150 mm:

SV1-XXXX: rope extension (150...4995 mm)
SV2-XXXX: rope extension (5000...19.995 mm)
SV3-XXXX: rope extension (20.000...40.000 mm)

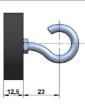


#### Magnetic clamp - MGG1

Use the magnetic clamp to quickly attach the rope to metallic objects without any assembly time. A rubber coating provides gentle contact (e. g. on varnished surfaces) and prevents from slipping due to vibration.

The magnet consists of a neodym core for an increased adhesive force of 260 N. The hook makes it easy to attach the rope clip.





### ACCESSORIES ANALOG Output

Cable with connector M12, 4 poles, shielded					
K4P2M-S-M12	2 m, connector straight				
K4P5M-S-M12	5 m, connector straight				
K4P10M-S-M12	10 m, connector straight				
K4P2M-SW-M12	2 m, connector angular				
K4P5M-SW-M12	5 m, connector angular				
K4P10M-SW-M12	10 m, connector angular				





Mating Connector M12, 4 poles, shielded		
D4-G-M12-S	straight, M12 for self assembly	
D4-W-M12-S	angular, M12 for self assembly	
	protection class: IP67	
	temperature: -25+90 °C	
	cable passage: ø 48 mm	
	wire cross-section: 0.140.34 mm²	
	mode of connection: spring cage	

#### Digital display - PAXD ( for Potentiometer)

Use the PAXD display to visualise the measured distance of the position transducer with a potentiometer as sensor element. A transmission of the measurement data to a computer or PLC can be done with interface plug-in cards.

Inputs: Potentiometer signal

Analog output (plug-in cards): 0...20 mA, 4...20 mA, 0...10 V

Serial interfaces (plug-in cards): RS485, RS232, DeviceNet, USB, Profibus, Relay output, Transistor output

Protection class: IP65 (Front panel)

Display: 5 digits

PAXD000B: 1 channel, power supply: 85 to 250 VAC
PAXD001B: 1 channel, power supply:: 11 to 36 VDC/24 VAC

For further information please see the data sheet of the PAXD display series





# ACCESSORIES ANALOG OUTPUT

#### Digital displays PAXP (1 channel) and PAXDP (2 channels) for sensors with analog output signals 0..10V or 4..20 mA

Use the PAXD or PAXDP display to visualise the measured distance of transducers with an analog output signal. A transmission of the measurement data to a computer or PLC can be done with interface plug-in cards.

Inputs: 0...10 V or 4...20 mA, 2 independent counters (for PAXDP)

Analog output (plug-in cards): 0...20 mA, 4...20 mA, 0...10 V

Serial interfaces (plug-in cards): RS485, RS232, DeviceNet, USB, Profibus, Relay output, Transistor output

Protection class: IP65 (front panel)

Display: 5 digits

PAXP000B: 1 channel, power supply: 85 to 250 VAC
PAXP001B: 1 channel, power supply: 11 to 36 VDC/24 VAC
PAXDP000B: 2 channels, power supply: 85 to 250 VAC
PAXDP001B: 2 channels, power supply: 11 to 36 VDC/24 VACC

For further information please see the PAXD and PAXDP data sheet.



# ACCESSORIES DIGITAL OUTPUT INCREMENTAL

Cable with connecto	r M12, 8 poles, shielded
K8P2M-S-M12	2 m, connector straight
K8P5M-S-M12	5 m, connector straight
K8P10M-S-M12	10 m, connector straight
K8P2M-SW-M12	2 m, connector angular
K8P5M-SW-M12	5 m, connector angular
K8P10M-SW-M12	10 m, connector angular

Mating connector M12, 8 poles, shielded		
D8-G-M12-S	mating connector straight	
D8-W-M12-S	mating connector angular	
	protection class: IP67	
	temperature: -25+90 °C	
	cable passage: ø 48 mm	
	wire diameter: 0.140.34 mm²	

# Mating connector M23, 12 poles CON012-S straight, metal housing wire diameter: AWG 16...26 mm² cable diameter: Ø 5.5...10 mm

CON012-S

#### Digital distance and speed display - WAY-D for incremental output signals

Use the WAY-D display to visualise the measured distance or the speed (tachometer) of the position transducer. A transfer of data to a PC or PLC can be done with the RS232 interface of the WAY-DR.

Protection class: IP65 (front panel)
Display: 6 digits
Supply: 115 / 250 VAC

Output Linedriver L (TTL, RS422):

WAY-DS-5VH: display only, input level TTL

WAY-DG-5VH: display with two presets and switching outputs, input level TTL WAY-DR-5VH: display with serial interface RS232 / RS485, input level TTL

Output Push-Pull G:

WAY-DS: display only, input level HTL

WAY-DG: display with two presets and switching outputs, input level HTL WAY-DR: display with serial interface RS232 / RS485, input level HTL

For further information please see the WAY-D data sheet.



### ACCESSORIES DIGITAL OUTPUT ABSOLUTE SSI

#### Digital distance and speed display - WAY-SSI for SSI output signals

Use the WAY-SSI display to visualise the measured distance or the speed (tachometer) of the position transducer. A transfer of data to a PC or PLC can be done with the RS232 interface of the WAY-SSI-R.

Protection class: IP65 (front panel)
Display: 6 digits
Supply: 115 / 250 VAC
WAY-SSI-S: display only

WAY-SSI-A: display with analog output

WAY-SSI-G: display with two presets and switching outputs

WAY-SSI-R: display with serial interface RS232 / RS485

For further information please see the WAY-SSI data sheet.





# MECHANICAL DATA

Measurement Range	Extraction Force		Speed	Acceleration
[mm]	F <sub>min</sub> [N]	F <sub>max</sub> [N]	V <sub>max</sub> [m/s]	a <sub>max</sub> [m/s²]
1000	4.2	5.4	10	140
1500	4.2	5.4	10	140
2000	5.0	6.4	10	140
2500	5.0	6.4	10	140
3000	5.0	6.4	10	140

<sup>\*</sup> reduced to 60 % when option IP67 is used

# INSTALLATION

 Mount the sensor at the designated place by using the fixing holes before extracting the rope and before attaching the rope to the measuring target.

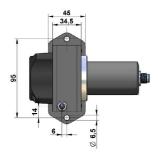


- Open the rope clip after the sensor is fully mounted and extract the measuring rope. Hook the rope clip on the measuring object and close the bracket of the clip. For safety reasons put a screw driver trough the clip to extract the rope.
- Check the track of the measuring target on collision with the sensor housing and on exceeding the specified measurement range. When installing the sensor make sure that the rubber stopper does not touch the rope outlet.
- Connect the electronics according to the sensor type. When laying the cables be careful not to under-run the minimal allowed bending radius of the cable (5 x cable diameter).
- The rope must be extracted from the sensor **vertically**. The maximum variation from the vertical is 3°. Avoid carefully extracting the rope at an inclination, since the durability of the instrument would shorten considerably. If it is not possible to keep the limit of 3°, a deflection pulley has to be used.
- The measuring range begins after approximately 2 mm extracted rope (=zero point). The mechanical reserve at the end of the measuring range is about 20 mm.
- When mounting outdoors protect the sensor and the rope from icing at temperatures below 0 °C.
- · Guide the rope preferably in corners or guarded in channels to prevent pollution or accidental touch.
- When operating the sensor, take care **not to let the rope snap back** by mistake or extract the rope **over the specified measurement range,** as this might destroy the sensor.
- Maintenance: These instruments are maintenance-free. If however, the rope is soiled due to adverse environmental conditions, it can be cleaned with a cloth drenched in resin-free machine oil.

#### Mounting: standard rope outlet, rope outlet sideways top (S1)

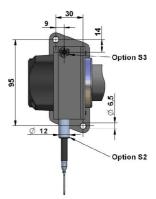
The sensor is usually installed by using the regular mounting plate (see technical drawing on page 4).

By disassembling the mounting plate, there are 4 threads (2 x M3, 2 x M5) in the sensor housing for alternative installation.



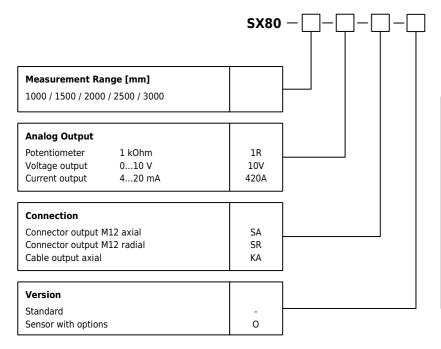
#### Mounting: rope outlet sideways bottom (S2), rope outlet bottom (S3)

Sensors with option rope outlet S2 and S3 have a modified base plate.





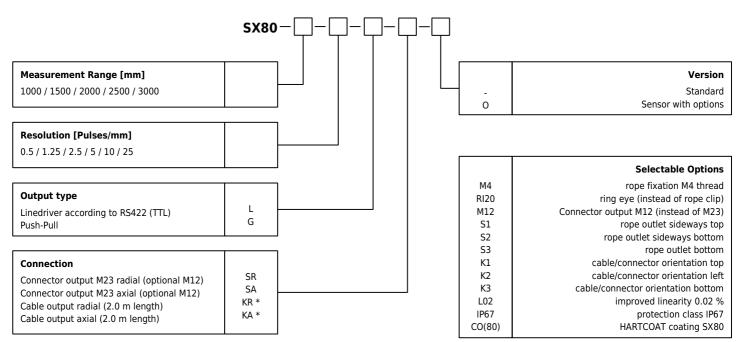
# ORDER CODE ANALOG OUTPUT



	Selectable Options
M4	rope fixation be M4 thread
RI20	ring eye (instead of rope clip)
S1	rope outlet sideways top
S2	rope outlet sideways bottom
S3	rope outlet bottom
IN	inverted output signal
L05	improved linearity 0.05 %
L10	improved linearity 0.10 %
SSB8	stainless steel bearings
TEMP-40-SX-ST	increased temperature range low -40+85°C
TEMP120*	increased temperature range high -20+120 °C
IP67	protection class IP67
CO(80)	HARTCOAT coating SX80
ICP(80)	increased corrosion protection SX80

<sup>\*</sup> only for 1R in combination with KA

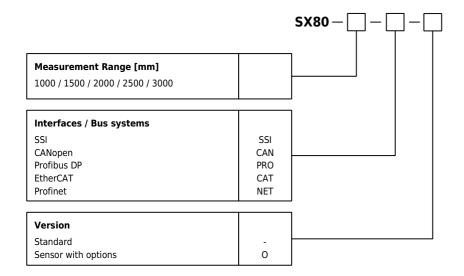
# ORDER CODE DIGITAL OUTPUT INCREMENTAL



<sup>\*</sup> for linedriver: 10 wires (with additional sensor lines) for push-pull: 8 wires (without additional sensor lines)



# ORDER CODE DIGITAL OUTPUT ABSOLUTE



	Selectable Options
M4	rope fixation M4 thread
RI20	ring eye (instead of rope clip)
S1	rope outlet sideways top
S2	rope outlet sideways bottom
S3	rope outlet bottom
K1	cable/connector orientation top
K2	cable/connector orientation left
K3	cable/connector orientation bottom
L02	improved linearity 0.02 %
IP67	protection class IP67
CO(80)	HARTCOAT coating SX80

# GENERAL ACCESSORIES

UR2	Deflection pulley	SV1-XXXX	rope extension (1504995 mm)
MGG1	Magnetic clamp	SV2-XXXX	rope extension (500019.995 mm)
		SV3-XXXX	rope extension (20.00040.000 mm)

# ACCESSORIES ANALOG OUTPUT

Cable with mating connector M12, 4 poles, shielded		
K4P2M-S-M12	2 m, straight connector	
K4P5M-S-M12	5 m, straight connector	
K4P10M-S-M12	10 m, straight connector	
K4P2M-SW-M12	2 m, angular connector	
K4P5M-SW-M12	5 m, angular connector	
K4P10M-SW-M12	10 m, angular connector	

Mating Connector M12, 4 poles, shielded		
D4-G-M12-S	straight, M12 for self assembly	
D4-W-M12-S	angular, M12 for self assembly	

Additional cable for	or cable output KA (2 m length is standard)
Kabel-TPE	order code for 1 m of additional TPE cable

Digital display 1	cnannel, 010V/420 mA	
PAXP000B	1 channel, supply: 85 to 250 VAC	
PAXP001B	1 channel, supply: 1136 VDC/24 VAC	
Digital display 2 channels, 010V/420 mA		
Digital display 2	channels, 010V/420 mA	
Digital display 2 PAXDP00B	channels, 010V/420 mA 2 channels, supply: 85 to 250 VAC	

Digital display 1 channel, Potentiometer		
PAXD000B	1 channel, supply: 85 to 250 VAC	
PAXD001B	1 channel, supply: 1136 VDC/24 VAC	



**CANopen output:** K5P2M-B-M12-CAN

K5P2M-SB-M12-CAN

K5P2M-S-M12-CAN

# ACCESSORIES DIGITAL OUTPUT INCREMENTAL

Cable with mating connector M12, 8 poles, shielded		
K8P2M-S-M12	2 m, straight connector	
K8P5M-S-M12	5 m, straight connector	
K8P10M-S-M12	10 m, straight connector	
K8P2M-SW-M12	2 m, angular connector	
K8P5M-SW-M12	5 m, angular connector	
K8P10M-SW-M12	10 m, angular connector	

# Cable with mating connector M23, 8 poles, shielded K8P2M-S-M23 2 m, straight connector K8P5M-S-M23 5 m, straight connector K8P10M-S-M23 10 m, straight connector

#### Mating Connector M23, 12 poles, shielded

CON012-S straight, M23 for self assembly, metal housing

Mating Connector M12, 8 poles, shielded		
D8-G-M12-S	straight, M12 for self assembly	
D8-W-M12-S	angular, M12 for self assembly	

Digital display 1 channel, Linedriver L (input level TTL, RS422)		
WAY-DS-5VH	display only	
WAY-DG-5VH	display with two presets and switching outputs	
WAY-DR-5VH	display with serial interface RS232 / RS485	

Digital display 1 channel, Push-Pull G		
WAY-DS	display only	
WAY-DG	display with two presets and switching outputs	
WAY-DR	display with serial interface RS232 / RS485	

2 m cable, plug female M12, 5 poles, open ends

2 m cable, connector male M12, 5 poles, plug female M12

2 m cable, connector male, M12, 5 poles, open ends

# ACCESSORIES DIGITAL OUTPUT ABSOLUTE

SSI output:		
K12P02M-S-M23-SSI	2 m cable, shielded, M23 connector straight	
K12P05M-S-M23-SSI	5 m cable, shielded, M23 connector straight	
K12P10M-S-M23-SSI	10 m cable, shielded, M23 connector straight	
K12P15M-S-M23-SSI	15 m cable, shielded, M23 connector straight	
CON012-S	Mating connector M23 shielded, straight, 12 poles	
Digital display 1 channel, for sensors with SSI signal		
WAY-SSI-S	display only	
WAY-SSI-A	display with analog output	
WAY-SSI-G	display with two presets and switching outputs	
WAY-SSI-R	display with serial interface RS232 / RS485	
Profibus DP:		
K5P2M-B-M12-PROF	2 m cable, plug female M12, 5 poles, open ends	
K5P2M-SB-M12-PROF	2 m cable, connector male M12, 5 poles, plug female M12	
K5P2M-S-M12-PROF	2 m cable, connector male, M12, 5 poles, open ends	
M12-PROF-AW	terminator	

EtherCAT / Profinet:	
K4P2M-S-M12-CAT	2 m cable, connector male M12, 4 poles, open ends
K4P5M-S-M12-CAT	5 m cable, connector male M12, 4 poles, open ends
K4P10M-S-M12-CAT	10 m cable, connector male M12, 4 poles, open ends
K4P2M-B-M12-CAT	2 m cable, plug female M12, 4 poles, open ends
K4P5M-B-M12-CAT	5 m cable, plug female M12, 4 poles, open ends
K4P10M-B-M12-CAT	10 m cable, plug female M12, 4 poles, open ends

Subject to change without prior notice.

